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continuous time systems and control solutions. In fact, as optimal control solutions are now often implemented digitally, contemporary control theory is now primarily concerned with discrete time systems and solutions.

Optimal control - Wikipedia

The solution of $x(k + 1) = (A +$

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$BF)x(k)$ reaches zero in, at most, n steps In the output feedback case, assigning the eigenvalues of $(A - KC)$ at zero ensures that the solution of the closed-loop system $x(k + 1) = (A + BF)x(k) - BFe(k)$ $e(k + 1) = (A - KC)e(k)$ reaches zero in, at most, $2n$ steps

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variables whose values evolve over time in a way that depends on the values they have at any given time and on the externally imposed values of input variables.

State-space representation - Wikipedia

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